Mechanising Turing Machines and Computability Theory in Isabelle





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Why Turing Machines?

 At the beginning, it was just a student project about computability.



Computability and Logic (5th. ed) Boolos, Burgess and Jeffrey

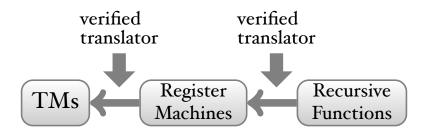
• found an inconsistency in the definition of halting computations (Chap. 3 vs Chap. 8)

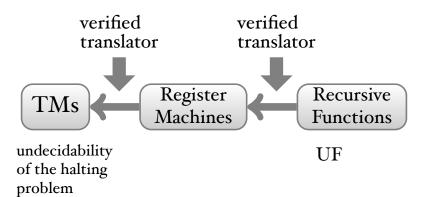
Some Previous Works

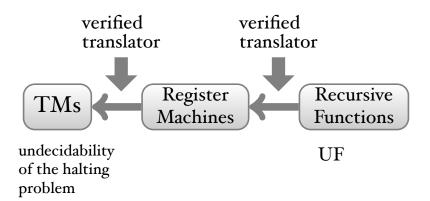
- Norrish formalised computability theory in HOL starting from the lambda-calculus
 - for technical reasons we could not follow him
 - some proofs use TMs (Wang tilings)
- Asperti and Ricciotti formalised TMs in Matita
 - no undecidability result ⇒ interest in complexity
 - their UTM operates on a different alphabet than the TMs it simulates

"In particular, the fact that the universal machine operates with a different alphabet with respect to the machines it simulates is annoying." [Asperti and Ricciotti]





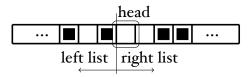




correct UTM by translation

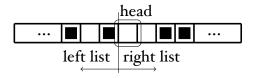
Turing Machines

• tapes are lists and contain 0s or 1s only



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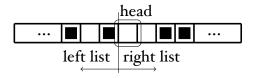


• *steps* function:

What does the TM calculate after it has executed *n* steps?

Turing Machines

tapes are lists and contain 0s or 1s only



- *steps* function:
 - What does the TM calculate after it has executed *n* steps?
- designate the *0*-state as "halting state" and remain there forever, i.e. have a *Nop*-action

Register Machines

• programs are lists of instructions

```
I ::= Goto L jump to instruction L
| Inc R increment register R by one
| Dec R L if content of R is non-zero, then decrement it by one otherwise jump to instruction L
```

Register Machines

Spaghetti Code!

instructions

I ::= Goto L $\mid Inc R$ $\mid Dec R L$

jump to instruction *L* increment register *R* by one if content of *R* is non-zero, then decrement it by one otherwise jump to instruction *L*

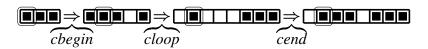
Recursive Functions

$$rec$$
 ::= Z zero-function $|$ S successor-function $|$ Id_m^n projection $|$ $Cn^n f gs$ composition $|$ $Pr^n f g$ primitive recursion $|$ $Mn^n f$ minimisation

- eval :: rec ⇒ nat list ⇒ nat
 can be defined by simple recursion
 (HOL has Least)
- you define
 - addition, multiplication, logical operations, quantifiers...
 - coding of numbers (Cantor encoding), UTM

Copy Turing Machine

• TM that copies a number on the input tape



 $copy \stackrel{def}{=} cbegin ; cloop ; cend$

Hoare Logic for TMs

Hoare-triples

```
{P} p {Q} \stackrel{def}{=} \forall tp.

if P tp holds then
\exists n. such that

is_final (steps (1, tp) p n) ∧

O holds for (steps (1, tp) p n)
```

Hoare Logic for TMs

• Hoare-triples and Hoare-pairs:

Some Derived Rules

$$\frac{P' \mapsto P \quad \{P\} \ p \ \{Q\} \quad Q \mapsto Q'}{\{P'\} \ p \ \{Q'\}}$$

$$\frac{\{P\} p_1 \{Q\} \quad \{Q\} p_2 \{R\}}{\{P\} p_1 ; p_2 \{R\}} \quad \frac{\{P\} p_1 \{Q\} \quad \{Q\} p_2 \uparrow}{\{P\} p_1 ; p_2 \uparrow}$$

Undecidability

 $contra \stackrel{def}{=} copy$; H; dither

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 Suppose H decides contra called with code of contra halts, then

```
P_1 \stackrel{def}{=} \lambda tp. \ tp = ([], \langle code \ contra \rangle)
P_2 \stackrel{def}{=} \lambda tp. \ tp = ([0], \langle (code \ contra, \ code \ contra) \rangle)
P_3 \stackrel{def}{=} \lambda tp. \ \exists \ k. \ tp = (0^k, \langle 0 \rangle)
```

$$\frac{\{P_1\} copy \{P_2\} \quad \{P_2\} H \{P_3\}}{\{P_1\} copy ; H \{P_3\}} \quad \{P_3\} dither \uparrow \\ \{P_1\} contra \uparrow$$

Undecidability

 $contra \stackrel{def}{=} copy ; H ; dither$

 Suppose H decides contra called with code of contra does not halt, then

```
Q_1 \stackrel{def}{=} \lambda tp. \ tp = ([], \langle code \ contra \rangle)
Q_2 \stackrel{def}{=} \lambda tp. \ tp = ([0], \langle (code \ contra, \ code \ contra) \rangle)
Q_3 \stackrel{def}{=} \lambda tp. \ \exists \ k. \ tp = (0^k, \langle 1 \rangle)
```

$$\frac{\{Q_1\} \operatorname{copy} \{Q_2\} \quad \{Q_2\} H \{Q_3\}}{\{Q_1\} \operatorname{copy} ; H \{Q_3\}} \quad \{Q_3\} \operatorname{dither} \{Q_3\}}{\{Q_1\} \operatorname{contra} \{Q_3\}}$$

Hoare Reasoning

reasoning is still quite demanding;
 the invariants of the copy-machine:

$$I_{1} n (l, r) \stackrel{def}{=} (l, r) = ([], I^{n}) \qquad \text{(starting state)}$$

$$I_{2} n (l, r) \stackrel{def}{=} \exists i j. \ 0 < i \land i + j = n \land (l, r) = (I^{i}, I^{j})$$

$$I_{3} n (l, r) \stackrel{def}{=} 0 < n \land (l, tl \ r) = (0::I^{n}, [])$$

$$I_{4} n (l, r) \stackrel{def}{=} 0 < n \land (l, r) = (I^{n}, [0, 1]) \lor (l, r) = (I^{n-1}, [1, 0, 1])$$

$$I_{0} n (l, r) \stackrel{def}{=} 1 < n \land (l, r) = (I^{n-2}, [1, 1, 0, 1]) \lor \text{(halting state)}$$

$$n = 1 \land (l, r) = ([], [0, 1, 0, 1])$$

$$J_{1} n (l, r) \stackrel{def}{=} \exists i j. \ i + j + 1 = n \land (l, r) = (I^{i}, 1::1::0^{j} @ I^{j}) \land 0 < j \lor$$

$$0 < n \land (l, r) = ([], 0::1::0^{n} @ I^{n}) \text{(starting state)}$$

$$J_{0} n (l, r) \stackrel{def}{=} 0 < n \land (l, r) = ([0], 1::0^{n} @ I^{n}) \text{(halting state)}$$

$$K_{1} n (l, r) \stackrel{def}{=} 0 < n \land (l, r) = ([0], 1::0^{n} @ I^{n}) \text{(halting state)}$$

$$K_{0} n (l, r) \stackrel{def}{=} 0 < n \land (l, r) = ([0], 1^{n} @ 0::1^{n}) \text{(halting state)}$$

Midway Conclusion

- feels awfully like reasoning about machine code
- compositional constructions / reasoning not at all frictionless
- sizes

sizes:

UF 140843 constructors
URM 2 Mio instructions
UTM 38 Mio states

*old version: URM (12 Mio) UTM (112 Mio)

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 an observation: our treatment of recursive functions is a mini-version of the work by Myreen & Owens about deeply embedding HOL

Stealing From Other Works

- Jensen, Benton, Kennedy (2013), High-Level Separation Logic for Low-Level Code
- Myreen (2008), Formal Verification of Machine-Code Programs, PhD thesis
- Klein, Kolanski, Boyton (2012), Mechanised Separation Algebra

Better Composability

- an idea from Jensen, Benton, Kennedy who looked at X86 assembly programs and macros
- assembly for TMs:

```
move\_one\_left \stackrel{def}{=} 
 \Lambda \ exit. 
Inst (L, exit) (L, exit) ;
Label \ exit
```

⇒ represent "state" labels as functions (with bound variables ⇒ locality)

Better Composability

```
move_left_until_zero =

\[
\Lambda \text{ start exit.} \\
Label \text{ start;} \\
if_zero \text{ exit;} \\
move_left; \\
jmp \text{ start;} \\
Label \text{ exit.} \\
Label \text{ exit.} \\
\]
```

```
if_zero e \stackrel{def}{=} \Lambda exit. Inst (W_0, e), (W_1, exit); Label exit imp e \stackrel{def}{=} Inst (W_0, e), (W_1, e)
```

The Trouble With Hoare-Triples

Whenever we wanted to prove

- (1) we had to find a termination order proving that *p* terminates (not easy)
- (2) we had to find invariants for each state (not easy either)

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very little opportunity for automation

Separation Algebra

- use some infrastructure introduced by Klein et al in Isabelle/HOL
- and an idea by Myreen

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p, c, q will be assertions in a separation logic e.g. $\{st \ i \star hd \ n \star ones \ u \ v \star zero \ (v+1)\}$

Separation Triples

c can be i: [move_left_until_zero]: j

Automation

 we introduced some tactics for handling sequential programs

$$\{p\}\ i:[c_1;...;c_n]:j\{q\}$$

• for loops we often only have to do inductions on the length of the input (e.g. how many *I*s are on the tape)

Automation

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- for loops we often only have to do inductions on the length of the input (e.g. how many *I*s are on the tape)
- these macros allow us to completely get rid of register machines

Conclusion

- What started out as a student project, turned out to be much more fun than first thought.
- Where can you claim that you proved the correctness of a 38 Mio instruction program. (ca. 7000 is the soa 2)
- We learned a lot about current verification technology for low-level code (we had no infrastructure: CPU model).