

# A Formalised Theory of Turing Machines in Isabelle/HOL

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**Abstract**—Isabelle/HOL is an interactive theorem prover based on classical logic. While classical reasoning allow users to take convenient shortcuts in some proofs, it precludes *direct* reasoning about decidability: every boolean predicate is either true or false because of the law of excluded middle. The only way to reason about decidability in a classical theorem prover, like Isabelle/HOL, is to formalise a concrete model for computation. In this paper we formalise Turing machines and relate them to register machines.

**Keywords**—Turing Machines, Decidability, Isabelle/HOL;

## I. INTRODUCTION

We formalised in earlier work the correctness proofs for two algorithms in Isabelle/HOL—one about type-checking in LF [4] and another about deciding requests in access control [6]. The formalisations uncovered a gap in the informal correctness proof of the former and made us realise that important details were left out in the informal model for the latter. However, in both cases we were unable to formalise in Isabelle/HOL computability arguments about the algorithms. The reason is that both algorithms are formulated in terms of inductive predicates. Suppose  $P$  stands for one such predicate. Decidability of  $P$  usually amounts to showing whether  $P \vee \neg P$  holds. But this does *not* work in Isabelle/HOL, since it is a theorem prover based on classical logic where the law of excluded middle ensures that  $P \vee \neg P$  is always provable no matter whether  $P$  is constructed by computable means. The same problem would arise if we had formulated the algorithms as recursive functions, because internally in Isabelle/HOL, like in all HOL-based theorem provers, functions are represented as inductively defined predicates too.

The only satisfying way out of this problem in a theorem prover based on classical logic is to formalise a theory of computability. Norrish provided such a formalisation for the HOL4 theorem prover. He choose the  $\lambda$ -calculus as the starting point for his formalisation of computability theory, because of its “simplicity” [3, Page 297]. Part of his formalisation is a clever infrastructure for reducing  $\lambda$ -terms. He also established the computational equivalence between the  $\lambda$ -calculus and recursive functions. Nevertheless he concluded that it would be “appealing” to have formalisations for more operational models of computations, such as Turing machines or register machines. One reason is that many proofs in the literature use them. He noted however that in the context of theorem provers [3, Page 310]:

*“If register machines are unappealing because of their general fiddliness, Turing machines are an even more daunting prospect.”*

In this paper we took on this daunting prospect and provide a formalisation of Turing machines, as well as abacus machines (a kind of register machines) and recursive functions. To see the difficulties involved with this work, one has to understand that interactive theorem provers, like Isabelle/HOL, are at their best when the data-structures at hand are “structurally” defined, like lists, natural numbers, regular expressions, etc. Such data-structures come in the-orem provers with convenient reasoning infrastructures (for example induction principles, recursion combinators and so on). But this is *not* the case with Turing machines (and also not with register machines): underlying their definition is a set of states together with a transition function, both of which are not structurally defined. This means we have to implement our own reasoning infrastructure in order to prove properties about them. This leads to annoyingly lengthy and detailed formalisations. We noticed first the difference between both structural and non-structural “worlds” when formalising the Myhill-Nerode theorem, where regular expressions fared much better than automata [5]. However, with Turing machines there seems to be no alternative if one wants to formalise the great many proofs that use them. We give as example one proof—undecidability of Wang tilings—in Section III. The standard proof of this property uses the notion of *universal Turing machines*.

We are not the first who formalised Turing machines in a theorem prover: we are aware of the preliminary work by Asperti and Ricciotti [1]. They describe a formalisation of Turing machines in the Matita theorem prover. They report that the informal proofs from which they started are not “sufficiently accurate to be directly used as a guideline for formalization” [1, Page 2]. For our formalisation we followed the proofs from the textbook [2] and found that the description is quite detailed. Some details are left out however: for example, it is only shown how the universal Turing machine is constructed for Turing machines computing unary functions. We had to figure out a way to generalize this result to  $n$ -ary functions. Similarly, when compiling recursive functions to abacus machines, the textbook again only shows how it can be done for 2- and 3-ary functions, but in the formalisation we need arbitrary function. But the

general ideas for how to do this are clear enough in [2].

The main difference between our formalisation and the one by Asperti and Ricciotti is that their universal machines

“In particular, the fact that the universal machine operates with a different alphabet with respect to the machines it simulates is annoying.”

## Contributions:

### II. FORMALISATION

### III. WANG TILES

Used in texture mappings - graphics

### IV. RELATED WORK

The most closely related work is by Norrish. He bases his approach on lambda-terms. For this he introduced a clever rewriting technology based on combinators and de-Brujin indices for rewriting modulo  $\beta$ -equivalence (to keep it manageable)

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