

# Mechanising Turing Machines and Computability Theory in Isabelle



Jian Xu



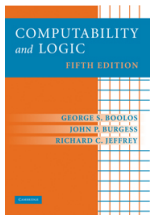
Xingyuan Zhang

PLA University of Science and Technology

Christian Urban  
King's College London

# Why Turing Machines?

- At the beginning, it was just a student project about computability.



Computability and Logic (5th. ed)  
Boolos, Burgess and Jeffrey

- found an inconsistency in the definition of halting computations (Chap. 3 vs Chap. 8)

# Some Previous Works

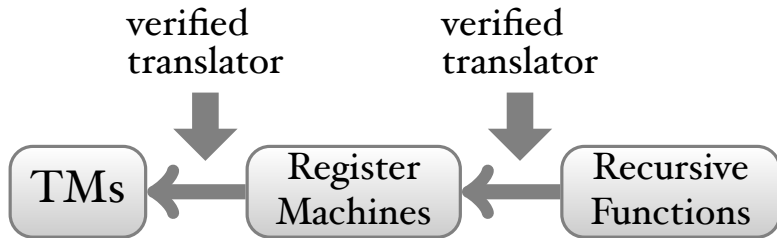
- Norrish formalised computability theory in HOL starting from the lambda-calculus
  - for technical reasons we could not follow his work
  - some proofs use TMs (Wang tilings)
- Asperti and Ricciotti formalised TMs in Matita
  - no undecidability result  $\Rightarrow$  interest in complexity
  - their UTM operates on a different alphabet than the TMs it simulates

*"In particular, the fact that the universal machine operates with a different alphabet with respect to the machines it simulates is annoying." [Asperti and Ricciotti]*

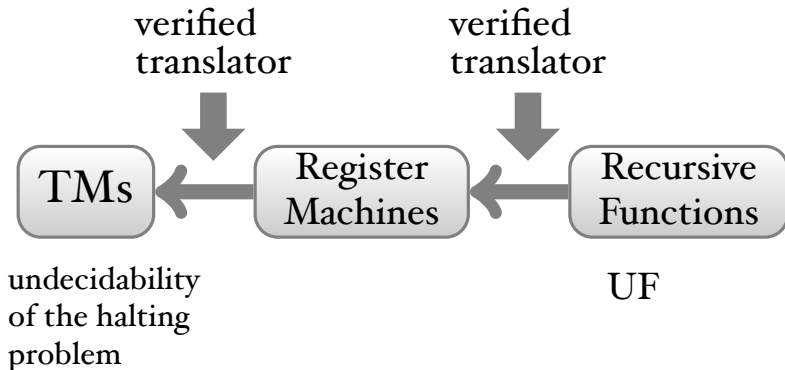
# The Big Picture



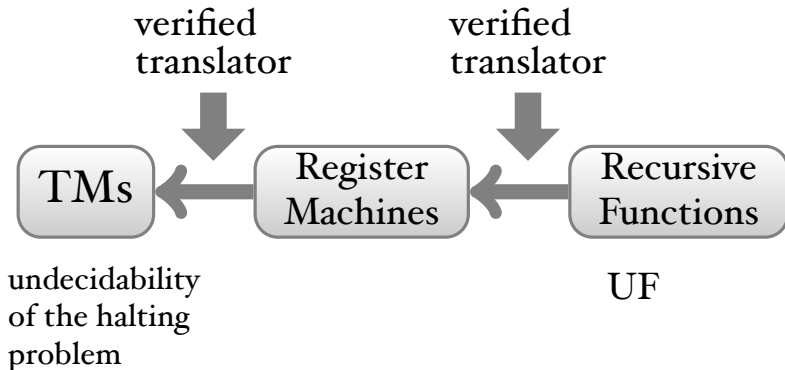
# The Big Picture



# The Big Picture



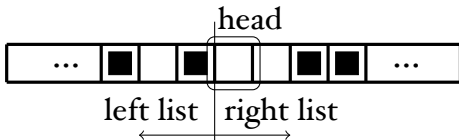
# The Big Picture



a correct UTM by translation

# Turing Machines

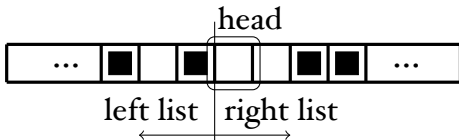
- tapes are lists and contain 0s or 1s only





# Turing Machines

- tapes are lists and contain 0s or 1s only

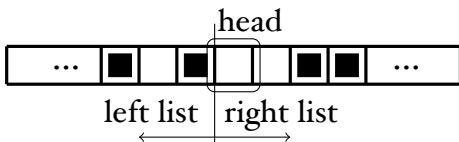


- *steps* function:

What does the TM calculate after it has executed  $n$  steps?

# Turing Machines

- tapes are lists and contain 0s or 1s only



- *steps* function:  
What does the TM calculate after it has executed  $n$  steps?
- designate the 0-state as "halting state" and remain there forever, i.e. have a *Nop*-action

# Register Machines

- programs are lists of instructions

$I ::=$	$Goto L$	jump to instruction $L$
	$Inc R$	increment register $R$ by one
	$Dec R L$	if the content of $R$ is non-zero, then decrement it by one otherwise jump to instruction $L$

# Register Machines

- programs are lists of instructions

$I ::=$	$Goto L$	jump to instruction $L$
	$Inc R$	increment register $R$ by one
	$Dec R L$	if the content of $R$ is non-zero, then decrement it by one otherwise jump to instruction $L$

Spaghetti Code!

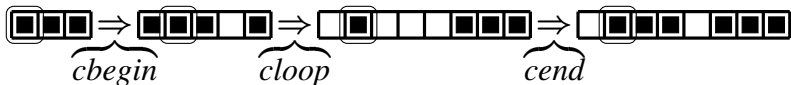
# Recursive Functions

$rec ::= Z$	zero-function
$S$	successor-function
$Id_m^n$	projection
$Cn^n f g s$	composition
$Pr^n f g$	primitive recursion
$Mn^n f$	minimisation

- $eval :: rec \Rightarrow nat\ list \Rightarrow nat$   
can be defined by simple recursion  
(HOL has *Least*)
- you define
  - addition, multiplication, logical operations, quantifiers...
  - coding of numbers (Cantor encoding), UF

# Copy Turing Machine

- TM that copies a number on the input tape

$$\text{copy} \stackrel{\text{def}}{=} \text{cbegin} ; \text{cloop} ; \text{cend}$$

 $\text{cbegin} \stackrel{\text{def}}{=}$ 

$$[(W_0, 0), (R, 2), (R, 3), \\ (R, 2), (W_1, 3), (L, 4), \\ (L, 4), (L, 0)]$$
 $\text{cloop} \stackrel{\text{def}}{=}$ 

$$[(R, 0), (R, 2), (R, 3), \\ (W_0, 2), (R, 3), (R, 4), \\ (W_1, 5), (R, 4), (L, 6), \\ (L, 5), (L, 6), (L, 1)]$$
 $\text{cend} \stackrel{\text{def}}{=}$ 

$$[(L, 0), (R, 2), (W_1, 3), \\ (L, 4), (R, 2), (R, 2), \\ (L, 5), (W_0, 4), (R, 0), \\ (L, 5)]$$

# Hoare Logic for TMs

- Hoare-triples

$$\{P\} p \{Q\} \stackrel{\text{def}}{=}$$

$\forall tp.$

if  $P$   $tp$  holds then

$\exists n.$  such that

$is\_final (steps (l, tp) p n) \wedge$

$Q$  holds\_for  $(steps (l, tp) p n)$

# Hoare Logic for TMs

- Hoare-triples and Hoare-pairs:

$$\{P\} p \{Q\} \stackrel{\text{def}}{=}$$

$\forall tp.$

if  $P$   $tp$  holds then

$\exists n.$  such that

$is\_final (steps (l, tp) p n) \wedge$

$Q$  holds\_for  $(steps (l, tp) p n)$

$$\{P\} p \uparrow \stackrel{\text{def}}{=}$$

$\forall tp.$

if  $P$   $tp$  holds then

$\forall n. \neg is\_final (steps (l, tp) p n)$



# Some Derived Rules

$$\frac{P' \mapsto P \quad \{P\} p \{Q\} \quad Q \mapsto Q'}{\{P'\} p \{Q'\}}$$

$$\frac{\{P\} p_1 \{Q\} \quad \{Q\} p_2 \{R\}}{\{P\} p_1 ; p_2 \{R\}} \quad \frac{\{P\} p_1 \{Q\} \quad \{Q\} p_2 \uparrow}{\{P\} p_1 ; p_2 \uparrow}$$

# Undecidability

*contra*  $\stackrel{\text{def}}{=} \text{copy} ; H ; \text{dither}$

# Undecidability

$contra \stackrel{def}{=} copy ; H ; dither$

- Suppose  $H$  decides  $contra$  called with code of  $contra$  halts, then

$$P_1 \stackrel{def}{=} \lambda tp. tp = ([], \langle code\ contra \rangle)$$

$$P_2 \stackrel{def}{=} \lambda tp. tp = ([0], \langle (code\ contra, code\ contra) \rangle)$$

$$P_3 \stackrel{def}{=} \lambda tp. \exists k. tp = (0^k, \langle 0 \rangle)$$

$$\frac{\frac{\{P_1\} copy \{P_2\} \quad \{P_2\} H \{P_3\}}{\{P_1\} copy ; H \{P_3\}} \quad \{P_3\} dither \uparrow}{\{P_1\} contra \uparrow}}$$

# Undecidability

$contra \stackrel{def}{=} copy ; H ; dither$

- Suppose  $H$  decides  $contra$  called with code of  $contra$  does *not* halt, then

$$Q_1 \stackrel{def}{=} \lambda tp. tp = ([], \langle code\ contra \rangle)$$

$$Q_2 \stackrel{def}{=} \lambda tp. tp = ([0], \langle (code\ contra, code\ contra) \rangle)$$

$$Q_3 \stackrel{def}{=} \lambda tp. \exists k. tp = (0^k, \langle 1 \rangle)$$

$$\frac{\frac{\{Q_1\} copy \{Q_2\} \quad \{Q_2\} H \{Q_3\}}{\{Q_1\} copy ; H \{Q_3\}} \quad \{Q_3\} dither \{Q_3\}}{\{Q_1\} contra \{Q_3\}}$$

# Hoare Reasoning

- reasoning is quite demanding, e.g. the invariants of the copy-machine:

---

$$I_1 n(l, r) \stackrel{\text{def}}{=} (l, r) = ([], I^n) \quad \text{(starting state)}$$

$$I_2 n(l, r) \stackrel{\text{def}}{=} \exists i j. 0 < i \wedge i + j = n \wedge (l, r) = (I^i, I^j)$$

$$I_3 n(l, r) \stackrel{\text{def}}{=} 0 < n \wedge (l, tl\ r) = (0::I^n, [])$$

$$I_4 n(l, r) \stackrel{\text{def}}{=} 0 < n \wedge (l, r) = (I^n, [0, 1]) \vee (l, r) = (I^{n-1}, [1, 0, 1])$$

$$I_0 n(l, r) \stackrel{\text{def}}{=} 1 < n \wedge (l, r) = (I^{n-2}, [1, 1, 0, 1]) \vee \quad \text{(halting state)} \\ n = 1 \wedge (l, r) = ([], [0, 1, 0, 1])$$

---

$$J_1 n(l, r) \stackrel{\text{def}}{=} \exists i j. i + j + 1 = n \wedge (l, r) = (I^i, 1::1::0^j @ I^j) \wedge 0 < j \vee \\ 0 < n \wedge (l, r) = ([], 0::1::0^n @ I^n) \quad \text{(starting state)}$$

$$J_0 n(l, r) \stackrel{\text{def}}{=} 0 < n \wedge (l, r) = ([0], 1::0^n @ I^n) \quad \text{(halting state)}$$

---

$$K_1 n(l, r) \stackrel{\text{def}}{=} 0 < n \wedge (l, r) = ([0], 1::0^n @ I^n) \quad \text{(starting state)}$$

$$K_0 n(l, r) \stackrel{\text{def}}{=} 0 < n \wedge (l, r) = ([0], I^n @ 0::I^n) \quad \text{(halting state)}$$

---

# Midway Conclusion

- feels awfully like reasoning about machine code
- compositional constructions / reasoning is not at all frictionless
- sizes

sizes:

UF	140843 constructors
URM	2 Mio instructions
UTM	38 Mio states

\*old version: URM (12 Mio) UTM (112 Mio)

# Midway Conclusion

- feels awfully like reasoning about machine code
- compositional constructions / reasoning is not at all frictionless
- sizes

sizes:

UF 140843 constructors

URM 2 Mio instructions

UTM 38 Mio states

- an observation: our treatment of recursive functions is a mini-version of the work by Myreen & Owens about deeply embedding HOL

# Inspiration from other Works



# Stealing from other Works

# Stealing from other Works

- Jensen, Benton, Kennedy (2013), *High-Level Separation Logic for Low-Level Code*
- Myreen (2008), *Formal Verification of Machine-Code Programs*, PhD thesis
- Klein, Kolanski, Boyton (2012), *Mechanised Separation Algebra*

# Better Composability

- an idea from Jensen, Benton & Kennedy who looked at X86 assembly programs and macros
- assembly for TMs:

*move\_one\_left*  $\stackrel{def}{=}$

$\Lambda$  *exit*.

*Inst* (*L*, *exit*) (*L*, *exit*) ;

*Label* *exit*

$\Rightarrow$  represent "state" labels as functions  
(with bound variables  $\Rightarrow$  locality)

# Better Composability

$move\_left\_until\_zero \stackrel{def}{=}$

$\Lambda start\ exit.$

*Label start ;*

*if\_zero exit ;*

*move\_left ;*

*jmp start ;*

*Label exit*

$if\_zero\ e \stackrel{def}{=} \Lambda\ exit.\ Inst\ (W_0, e), (W_1, exit); Label\ exit$

$jmp\ e \stackrel{def}{=} Inst\ (W_0, e), (W_1, e)$

# The Trouble With Hoare-Triples

- Whenever we wanted to prove

$$\{P\} p \{Q\}$$

- (1) we had to find invariants for each state  
(not easy)
- (2) we had to find a termination order proving that  $p$  terminates (not easy either)

# The Trouble With Hoare-Triples

- Whenever we wanted to prove

$$\{P\} p \{Q\}$$

- (1) we had to find invariants for each state  
(not easy)
- (2) we had to find a termination order proving that  $p$  terminates (not easy either)

very little opportunity for automation

# Separation Algebra

- use some infrastructure introduced by Klein et al in Isabelle/HOL
- and an idea by Myreen

$$\{p\} c \{q\}$$

$p$ ,  $c$ ,  $q$  will be assertions in a separation logic

# Separation Algebra

- use some infrastructure introduced by Klein et al in Isabelle/HOL
- and an idea by Myreen

$$\{p\} c \{q\}$$

$p$ ,  $c$ ,  $q$  will be assertions in a separation logic

e.g.  $\{st\ i \star hd\ n \star ones\ u\ v \star zero\ (v + 1)\}$



# Separation Triples

$$\{p\} c \{q\} \stackrel{\text{def}}{=}$$

$$\forall cf r.$$

$(p \star c \star r)$  *cf* implies

$\exists k. (q \star c \star r)$  (*run k cf*)

$c$  can be  $i:[\text{move\_left\_until\_zero}]:j$

# Automation

- we introduced some tactics for handling sequential programs

$$\{p\} i:[c_1 ; \dots ; c_n]:j \{q\}$$

- for loops we often only have to do inductions on the length of the input (e.g. how many *l*s are on the tape)

# Automation

- we introduced some tactics for handling sequential programs

$$\{p\} i:[c_1 ; \dots ; c_n]:j \{q\}$$

- for loops we often only have to do inductions on the length of the input (e.g. how many  $l$ s are on the tape)
- these macros allow us to completely get rid of register machines

# Conclusion

- What started out as a student project, turned out to be much more fun than first thought.
- Where can you claim that you proved the correctness of a 38 Mio instruction program?  
(ca. 7000 is the soa 😊)
- We learned a lot about current verification technology for low-level code (we had no infrastructure: CPU model).
- The existing literature on TMs & RMs leave out quite a bit of the story (not to mention contains bugs).