Reasoning about Turing Machines and Low-Level Code

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• in the past:

model a problem mathematically and proof properties about the model

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- needs elegance, is still very hard
- does not help with ensuring the correctness of running programs

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you would expect the trend would be to for example model C, implement your programs in C and verify the programs written in C (e.g. seL4)

- but actually people start to verify machine code directly (e.g. bignum arithmetic implemented in x86-64 - 700 instructions)
- CPU models exists, but the strategy is to use a small subset which you use in your programs

Why Turing Machines

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- found an inconsistency in the definition of halting computations (Chap. 3 vs Chap. 8)
- Norrish formalised computability via lambda-calculus (and nominal); Asperti and Riccioti formalised TMs but didn't get proper UTM

Turing Machines

tapes contain 0 or 1 only



steps function

What does the tape look like after the TM has executed n steps?

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What does the tape look like after the TM has executed n steps?

designate the O-state as halting state and remain there forever

Copy Turing Machines

• TM that copies a number on the input tape





Hoare Logic for TMs

• Hoare-triples and Hoare-pairs:

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\begin{array}{ll} \label{eq:product} \{P\} \ p \ \{Q\} \ \stackrel{def}{=} & \{P\} \ p \ \uparrow \ \stackrel{def}{=} \\ \forall \ tp. & \forall \ tp. \\ \ if \ P \ tp \ holds \ then & if \ P \ tp \ holds \ then \\ \exists \ n. \ such \ that & \forall \ n. \ \neg \ is\_final \ (steps \ (1, \ tp) \ p \ n) \\ \ is\_final \ (steps \ (1, \ tp) \ p \ n) \ \land \\ Q \ holds\_for \ (steps \ (1, \ tp) \ p \ n) \end{array}
```

Hoare Reasoning

• reasoning is still quite difficult—invariants

$I_1 n (l, r)$	def	(l, r) = ([], 0 ⁿ)	(starting state)	
I_2 n (l, r)	def	∃ i j. 0 〈 i ∧ i + j = n ∧ (l, r) = (0 ⁱ , 0 ^j)		
I ₃ n (l, r)	def	0 < n < (l, tl r) = (1::0 ⁿ , [])		
I_4 n (l, r)	def	$\stackrel{ef}{=} 0 \langle n \wedge (l, r) = (0^{n}, [1, 0]) \vee (l, r) = (0^{n-1}, [0, 1, 0])$		
I ₀ n (l, r)	def =	1 $\langle n \land (l, r) = (0^{n-2}, [0, 0, 1, 0]) \lor$ n = 1 $\land (l, r) = ([], [1, 0, 1, 0])$	(halting state)	
$J_1 n (l, r)$	def =	∃ i j. i + j + 1 = n ∧ (l, r) = (0 ⁱ , 0::0::1 ^j @ 0 ^j 0 ⟨ n ∧ (l, r) = ([], 1::0::1 ⁿ @ 0 ⁿ)	:1 ^j @ 0 ^j) ∧ 0 ⟨ j ∨ (starting state)	
$J_0 n (l, r)$	def =	0 ⟨ n ∧ (l, r) = ([1], 0::1 ⁿ @ 0 ⁿ)	(halting state)	
K ₁ n (l, r)	def =	$0 \langle n \land (l, r) = ([1], 0::1^{n} @ 0^{n})$	(starting state)	
K ₀ n (l, r)	def =	0 ⟨ n ∧ (l, r) = ([1], 0 ⁿ @ (1∷0 ⁿ))	(halting state)	

Register Machines

instructions

I ::= Inc R increment register R by one | Dec R L if content of R is non-zero, then decrement it by one otherwise jump to instruction L | Goto L jump to instruction L

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- addition, multiplication, ...
- logical operations, quantifiers...
- coding of numbers (Cantor encoding)
- UF

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- Recursive Functions \Rightarrow Register Machines
- Register Machines \Rightarrow Turing Machines



- UF (size: 140843)
- Register Machine (size: 2 Mio instructions)
- UTM (size: 38 Mio states)

old version: RM (12 Mio) UTM (112 Mio)

Separation Algebra

- introduced a separation algebra framework for register machines and TMs
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- looks awfully like "real" assembly code

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- we can semi-automate the reasoning for our small TMs
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- Conclusion: we have a playing ground for reasoning about low-level code; we work on automation