Mechanising Turing Machines and Computability Theory in Isabelle





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Why Turing Machines?

• At the beginning, it was just a student project about computability.



Computability and Logic (5th. ed) Boolos, Burgess and Jeffrey

• found an inconsistency in the definition of halting computations (Chap. 3 vs Chap. 8)

Some Previous Work

- Norrish formalised computability theory in HOL starting from the lambda-calculus
 - for technical reasons we could not follow him
 - some proofs use TMs (Wang tilings)

• Asperti and Ricciotti formalised TMs in Matita

Turing Machines

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What does the TM claclulate after it has executed *n* steps?

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• designate the 0-state as \Box alting stateänd remain there forever, i.e. have a Nop-action



instructions

I ::= Inc Rincrement register R by one| Dec R Lif content of R is non-zero,then decrement it by oneotherwise jump to instruction L| Goto Ljump to instruction L

Copy Turing Machines

• TM that copies a number on the input tape



Hoare Logic for TMs

• Hoare-triples and Hoare-pairs:

 $\begin{array}{l} \label{eq:product} \{P\} \ p \ \{Q\} \ \stackrel{def}{=} & \{P\} \ p \ \stackrel{def}{=} \\ \forall \ tp. & \forall \ tp. \\ \text{if } P \ tp \ \text{holds then} & \text{if } P \ tp \ \text{holds then} \\ \exists \ n. \ \text{such that} & \forall \ n. \ \neg \ is_final \ (steps \ (1, \ tp) \ p \ n) \\ is_final \ (steps \ (1, \ tp) \ p \ n) \ \land \\ Q \ holds \ for \ (steps \ (1, \ tp) \ p \ n) \end{array}$

Hoare Reasoning

• reasoning is still quite demanding; the invariants of the copy-machine:

 $I_1 n (l, r) \stackrel{def}{=} (l, r) = (I l, l^n)$ (starting state) $I_2 n(l, r) \stackrel{def}{=} \exists i j, 0 < i \land i + j = n \land (l, r) = (1^i, 1^j)$ $I_3 n (l, r) \stackrel{def}{=} 0 < n \land (l, tl r) = (0::1^n, [1])$ $I_{4} n (l, r) \stackrel{def}{=} 0 < n \land (l, r) = (1^{n}, [0, 1]) \lor (l, r) = (1^{n-1}, [1, 0, 1])$ $I_0 n(l, r) \stackrel{def}{=} l < n \land (l, r) = (l^{n-2}, [l, l, 0, 1]) \lor$ (halting state) $n = 1 \land (l, r) = ([1, [0, 1, 0, 1]))$ $J_1 n (l, r) \stackrel{def}{=} \exists i j, i + j + l = n \land (l, r) = (l^i, l::l::0^j @ l^j) \land 0 < j \lor$ $0 < n \land (l, r) = ([], 0::1::0^n @ 1^n)$ (starting state) $J_0 n (l, r) \stackrel{def}{=} 0 < n \land (l, r) = ([0], 1::0^n @ 1^n)$ (halting state) $K_1 n (l, r) \stackrel{def}{=} 0 < n \land (l, r) = ([0], 1::0^n @ 1^n)$ (starting state) $K_0 n (l, r) \stackrel{def}{=} 0 < n \land (l, r) = ([0], l^n @ 0;: l^n)$ (halting state)

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Recursive Functions

- addition, multiplication, ...
- logical operations, quantifiers...
- coding of numbers (Cantor encoding)
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- Recursive Functions \Rightarrow Register Machines
- Register Machines \Rightarrow Turing Machines



- UF (size: *140843*)
- Register Machine (size: 2 Mio instructions)
- UTM (size: 38 Mio states)

old version: RM (12 Mio) UTM (112 Mio)

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- introduced a separation algebra framework for register machines and TMs
- we can semi-automate the reasoning for our small TMs
- we can assemble bigger programs out of smaller components
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- we can semi-automate the reasoning for our small TMs
- we can assemble bigger programs out of smaller components
- looks awfully like ``real" assembly code
- Conclusion: we have a playing ground for reasoning about low-level code; we work on automation