

**Lecture 7: Myhill-Nerode Theorem**

**7.1 Word equivalence.** Consider a language  $L$  over an alphabet  $\Sigma$ . Two words  $x, y \in \Sigma^*$  are *L-equivalent*, written  $x \equiv_L y$ , iff for all words  $z \in \Sigma^*$ , we have  $xz \in L$  iff  $yz \in L$ . For example, if  $\Sigma = \{0, 1\}$  and  $A = \Sigma^*0\Sigma$ , then  $\equiv_A$  has four equivalence classes:

$$\begin{aligned} A_1 &= \Sigma^*00 \\ A_2 &= \Sigma^*01 \\ A_3 &= \Sigma^*10 \cup 0 \\ A_4 &= \Sigma^*11 \cup 1 \cup \varepsilon \end{aligned}$$

If  $\Sigma = \{0, 1\}$  and  $B = \{0^n1^n : n \geq 0\}$ , then  $\equiv_B$  has infinitely many equivalence classes:

$$\begin{aligned} B_- &= \{0^n1^m : m > n \geq 0\} \cup \Sigma^*1\Sigma^*0\Sigma^* \\ B_0 &= \{0^n1^n : n \geq 0\} \\ B_1 &= \{0^n1^{n-1} : n \geq 1\} \\ B_2 &= \{0^n1^{n-2} : n \geq 2\} \\ B_3 &= \{0^n1^{n-3} : n \geq 3\} \\ &\vdots \end{aligned}$$

The number of equivalence classes of  $\equiv_L$  is called the *index* of the language  $L$ . In particular, the index of  $A$  is 4, and the index of  $B$  is  $\infty$ .

**7.2 Word equivalence is a right congruence.** The equivalence  $\equiv_L$  has the following two properties:

- (1) If  $x \equiv_L y$  and  $x \in L$ , then  $y \in L$ .
- (2) If  $x \equiv_L y$ , then  $xa \equiv_L ya$ .

They are immediate consequences of the definition.

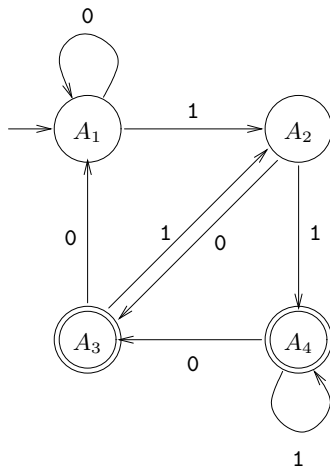
**7.2 Myhill-Nerode theorem, part 1.** The equivalence relation  $\equiv_L$  characterizes exactly what the state of an automaton that defines  $L$  needs to remember about the read portion of the input: if the read portion of the input is  $x$ , then the state needs to remember the equivalence class  $[x]_{\equiv_L}$ . This is sufficient, because if  $x \equiv_L y$ , then it does not matter if the read portion of the input was  $x$  or  $y$ ; all that matters for deciding whether to accept or reject is the future portion of the input, say  $z$ , because  $xz \in L$  iff  $yz \in L$ . It is also necessary, because if  $x \not\equiv_L y$ , then there is some possible future portion  $z$  of the input such that  $xz$  needs to be accepted and  $yz$  rejected (or vice versa). This is formalized by the following two theorems.

**Theorem 7A.** If the index of a language  $A$  is  $k$ , then there is a  $k$ -state DFA  $M_A$  such that  $L(M_A) = A$ .

To see this, let  $A \subseteq \Sigma^*$  be a language with index  $k$ . Define the following finite automaton  $M_A = (Q, \Sigma, \delta, q_0, F)$ , whose states are the  $\equiv_A$ -equivalence classes:

$$\begin{aligned} Q &= \{[x]_{\equiv_A} : x \in \Sigma^*\}. \\ q &\in \delta(p, a) \text{ iff there exists a word } x \in p \text{ such that } xa \in q. \\ q_0 &= [\varepsilon]_{\equiv_A}. \\ q &\in F \text{ iff there exists a word } x \in q \text{ such that } x \in A. \end{aligned}$$

From (2) it follows that  $M_A$  is deterministic. From (1) it follows that for all states  $q \in Q$ , either  $q \cap A = \emptyset$  or  $q \subseteq A$ . Therefore, for every word  $x \in \Sigma^*$ , after reading input  $x$ , the DFA  $M_A$  ends up in the state  $[x]_{\equiv_A}$ , which accepts if  $x \in A$  and rejects if  $x \notin A$ . For  $A = \Sigma^*0\Sigma$ :



It can be shown that for every DFA  $D$ , the quotient automaton  $D/\approx$  is equal (up to renaming of states) to the DFA  $M_{L(D)}$ .

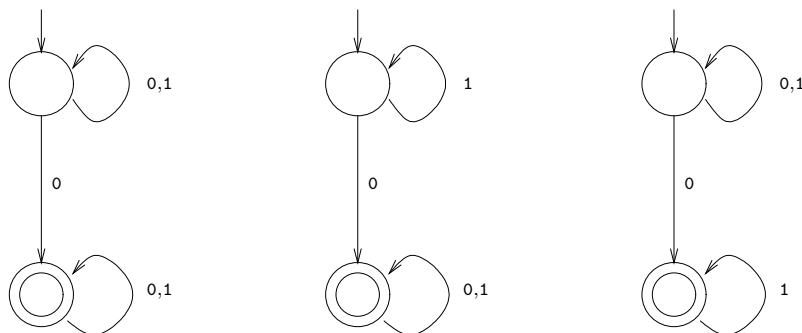
**7.3 Myhill-Nerode theorem, part 2.** In the previous section we saw that every language with finite index is regular; now we will see that every regular language has a finite index.

**Theorem 7B.** For every  $k$ -state DFA  $M$ , the index of  $L(M)$  is at most  $k$ .

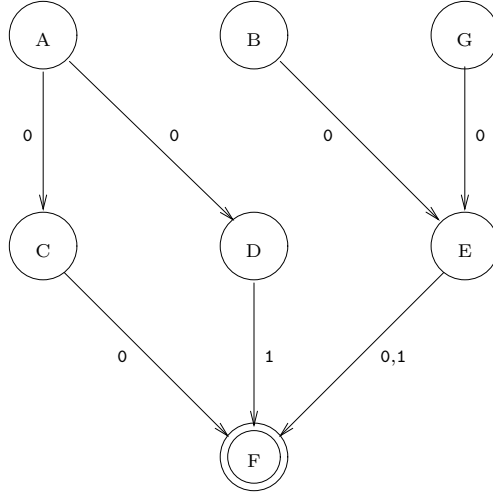
To see this, consider a DFA  $M$  over the alphabet  $\Sigma$ . For two words  $x, y \in \Sigma^*$ , let  $x \equiv_M y$  iff after reading input  $x$ , the DFA  $M$  ends up in the same state as after reading input  $y$ . The number of  $\equiv_M$ -equivalence classes is equal to the number of states of  $M$ , say  $k$ . If  $x \equiv_M y$ , then  $x \equiv_{L(M)} y$ , because inputs  $xz$  and  $yz$  always lead to the same state. Hence there can be no more  $\equiv_{L(M)}$ -equivalence classes than there are  $\equiv_M$ -equivalence classes; that is, the index of  $L(M)$  is at most  $k$ .

Theorem 7B can be used to show that a language is nonregular: it suffices to argue that its index is  $\infty$ . Theorem 7B can be strengthened to show that if  $M$  is reduced (i.e.,  $M = M/\approx$ ), then the index of  $L(M)$  is exactly  $k$ . From that and Section 7.1 it follows that for every regular language  $L$  there is a unique (up to renaming of states) minimal DFA (with the fewest number of states), and that this DFA can be obtained by applying the quotient construction to *any* DFA for  $L$ .

**7.4 Nondeterminism and minimality.** There may not be a unique minimal NFA for a regular language. For example, the following three automata all define the same language, namely  $\Sigma^*0\Sigma$ , and are all reduced:



**7.5 Bisimilarity.** For DFAs, if two states  $p$  and  $q$  are equivalent, then for all input letters  $a$ , also  $\delta(p, a)$  and  $\delta(q, a)$  are equivalent. By contrast, for NFAs, two states  $p$  and  $q$  may be equivalent even though there are no equivalent states in  $\delta(p, a)$  and  $\delta(q, a)$ . For instance, for the following NFA  $N$ , states A and B are equivalent even though no two of C, D, and E are equivalent:



$$\begin{aligned}
 L(N_A) &= L(N_B) = L(N_G) = \{00, 01\} \\
 L(N_C) &= \{0\} \\
 L(N_D) &= \{1\} \\
 L(N_E) &= \{0, 1\} \\
 L(N_F) &= \{\varepsilon\}
 \end{aligned}$$

For NFAs we can define a stronger concept than state equivalence called state bisimilarity, which corresponds to “recursive state equivalence”: two states  $p$  and  $q$  of an NFA  $M = (Q, \Sigma, \delta, q_0, F)$  are *bisimilar*, written  $p \approx_M^B q$ , iff the following three conditions are satisfied:

- (1)  $p \approx_M q$  (this can be weakened to  $p \approx_M^0 q$ ).
- (2) For all  $a \in \Sigma$  and all  $p' \in \delta(p, a)$ , there exists a state  $q' \in \delta(q, a)$  such that  $p' \approx_M^B q'$ .
- (3) For all  $a \in \Sigma$  and all  $q' \in \delta(q, a)$ , there exists a state  $p' \in \delta(p, a)$  such that  $p' \approx_M^B q'$ .

For the example automaton  $N$ , we have  $A \not\approx_N^B B$  but  $B \approx_N^B G$ .

**7.6 Minimization of nondeterministic automata.** When applied to NFAs, the minimization algorithm (suitably adjusted) computes state bisimilarity, not state equivalence. Recall the NFA  $N$  from Section 7.5:

A							
B	2						
C	1	1					
D	1	1	1				
E	1	1	1	1			
F	0	0	0	0	0		
G	2		1	1	1	0	
	A	B	C	D	E	F	G