

## Replacement Coursework 2 (Automata)

This coursework is worth 10%. It is about deterministic and non-deterministic finite automata. The coursework is due on ??? March at 5pm. Make sure the files you submit can be processed by just calling `scala <<filename.scala>>`.

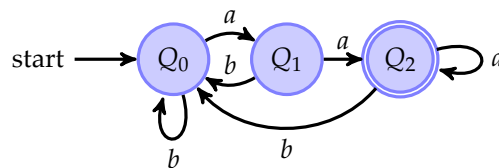
**Important:** Do not use any mutable data structures in your submission! They are not needed. This means you cannot use `ListBuffers`, for example. Do not use `return` in your code! It has a different meaning in Scala, than in Java. Do not use `var`! This declares a mutable variable. Make sure the functions you submit are defined on the “top-level” of Scala, not inside a class or object. Also note that when marking, the running time will be restricted to a maximum of 360 seconds on my laptop.

### Disclaimer

It should be understood that the work you submit represents your own effort! You have not copied from anyone else. An exception is the Scala code I showed during the lectures or uploaded to KEATS, which you can freely use.

### Part 1 (Deterministic Finite Automata)

There are many uses for Deterministic Finite Automata (DFAs), for example for testing whether a string matches a pattern or not. DFAs consist of some states (circles) and transitions (edges) between states. For example consider the DFA



has three states ( $Q_0$ ,  $Q_1$  and  $Q_2$ ), whereby  $Q_0$  is the starting state of the DFA and  $Q_2$  is the accepting state. The latter indicated by double lines. In general, a DFA can have any number of accepting states, but only a single starting state.

Transitions are edges between states labelled with a character. The idea is that if we are in state  $Q_0$ , say, and get an  $a$ , we can go to state  $Q_1$ . If we are in state  $Q_2$  and get an  $a$ , we can stay in state  $Q_2$ ; if we get a  $b$  in  $Q_2$ , then we have to go to state  $Q_0$ . The main point of DFAs is that if we are in a state and get a character, it is always clear which is the next state—there can only be at most one. The task of Part 1 is to implement such DFAs in Scala using partial functions for the transitions.

A string is accepted by a DFA, if we start in the starting state, follow all transitions according to the string; if we end up in an accepting state, then the

string is accepted. If not, the string is not accepted. The technical idea is that DFAs can be used to accept strings from *regular* languages.

## Tasks

- (1) Write a polymorphic function, called `share`, that decides whether two sets share some elements (i.e. the intersection is not empty). [1 Mark]
- (2) The transitions of DFAs will be implemented as partial functions. These functions will have the type (state, character)-pair to state, that is their input will be a (state, character)-pair and they return a state. For example the transitions of the DFA shown above can be defined as the following partial function:

```
val dfa_trans : PartialFunction[(State,Char), State] =
  { case (Q0, 'a') => Q1
    case (Q0, 'b') => Q0
    case (Q1, 'a') => Q2
    case (Q1, 'b') => Q0
    case (Q2, 'a') => Q2
    case (Q2, 'b') => Q0
  }
```

The main point of partial functions (as opposed to “normal” functions) is that they do not have to be defined everywhere. For example the transitions above only mention characters *a* and *b*, but leave out any other characters. Partial functions come with a method `isDefinedAt` that can be used to check whether an input produces a result or not. For example

```
dfa_trans.isDefinedAt((Q0, 'a'))
dfa_trans.isDefinedAt((Q0, 'c'))
```

gives `true` in the first case and `false` in the second. There is also a method `lift` that transformes a partial function into a “normal” function returning an optional value: if the partial function is defined on the input, the lifted function will return `Some`; if it is not defined, then `None`.

Write a function that takes a transition and a (state, character)-pair as arguments and produces an optional state (the state specified by the partial transition function whenever it is defined; if the transition function is undefined, return `None`). [1 Mark]

- (3) Write a function that “lifts” the function in (2) from characters to strings. That is, write a function that takes a transition, a state and a list of characters as arguments and produces the state generated by following the transitions for each character in the list. For example if you are in state `Q0` in the DFA above and have the list `List(a, a, a, b, b, a)`, then you need

to return the state  $Q_1$  (as option since there might not be such a state in general).

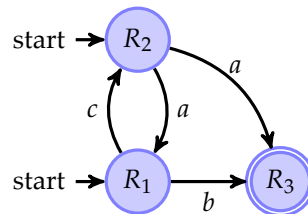
[1 Mark]

- (4) DFAs are defined as a triple: (starting state, transitions, set of accepting states). Write a function `accepts` that tests whether a string is accepted by an DFA or not. For this start in the starting state of the DFA, use the function under (3) to calculate the state after following all transitions according to the characters in the string. If the resulting state is an accepting state, return `true`; otherwise `false`.

[1 Mark]

## Part 2 (Non-Deterministic Finite Automata)

The main point of DFAs is that for every given state and character there is at most one next state (one if the transition is defined; none otherwise). However, this restriction to at most one state can be quite limiting for some applications.<sup>1</sup> Non-Deterministic Automata (NFAs) remove this restriction: there can be more than one starting state, and given a state and a character there can be more than one next state. Consider for example the NFA



where in state  $R_2$  if we get an  $a$ , we can go to state  $R_1$  or  $R_3$ . If we want to find out whether an NFA accepts a string, then we need to explore both possibilities. We will do this “exploration” in the tasks below in a breadth-first manner.

The feature of having more than one next state in NFAs will be implemented by having a *set* of partial transition functions (DFAs had only one). For example the NFA shown above will be represented by the set of partial functions

```
val nfa_trans : NTrans = Set(
  { case (R1, 'c') => R2 },
  { case (R1, 'b') => R3 },
  { case (R2, 'a') => R1 },
  { case (R2, 'a') => R3 }
)
```

The point is that the 3rd element in this set states that in  $R_2$  and given an  $a$ , we can go to state  $R_1$ ; and the 4th element, in  $R_2$ , given an  $a$ , we can also go to

<sup>1</sup>Though there is a curious fact that every (less restricted) NFA can be translated into an “equivalent” DFA, whereby accepting means accepting the same set of strings. However this might increase drastically the number of states in the DFA.

state  $R_3$ . When following transitions from a state, we have to look at all partial functions in the set and generate the set of *all* possible next states.

### Tasks

- (5) Write a function `nnext` which takes a transition set, a state and a character as arguments, and calculates all possible next states (returned as set). [1 Mark]
- (6) Write a function `nnexts` which takes a transition set, a *set* of states and a character as arguments, and calculates *all* possible next states that can be reached from any state in the set. [1 Mark]
- (7) Like in (3), write a function `nnextss` that lifts `nnexts` from (6) from single characters to lists of characters. [1 Mark]
- (8) NFAs are also defined as a triple: (set of starting states, set of transitions, set of accepting states). Write a function `naccepts` that tests whether a string is accepted by an NFA or not. For this start in all starting states of the NFA, use the function under (7) to calculate the set of states following all transitions according to the characters in the string. If the resulting set of states shares at least a single state with the set of accepting states, return `true`; otherwise `false`. Use the function under (1) in order to test whether these two sets of states share any states or not. [1 Mark]
- (9) Since we explore in functions (6) and (7) all possible next states, we decide whether a string is accepted in a breadth-first manner. (Depth-first would be to choose one state, follow all next states of this single state; check whether it leads to an accepting state. If not, we backtrack and choose another state). The disadvantage of breadth-first search is that at every step a non-empty set of states are “active”... states that need to be followed at the same time. Write similar functions as in (7) and (8), but instead of returning states or a boolean, calculate the number of states that need to be followed in each step. The function `max_accept` should then return the maximum of all these numbers.

As a test case, consider again the NFA shown above. At the beginning the number of active states will be 2 (since there are two starting states, namely  $R_1$  and  $R_2$ ). If we get an  $a$ , there will be still 2 active states, namely  $R_1$  and  $R_3$  both reachable from  $R_2$ . There is no transition for  $a$  and  $R_1$ . So for a string, say,  $ab$  which is accepted by the NFA, the maximum number of active states is 2 (it is not possible that all three states of this NFA are active at the same time; is it possible that no state is active?). [2 Marks]